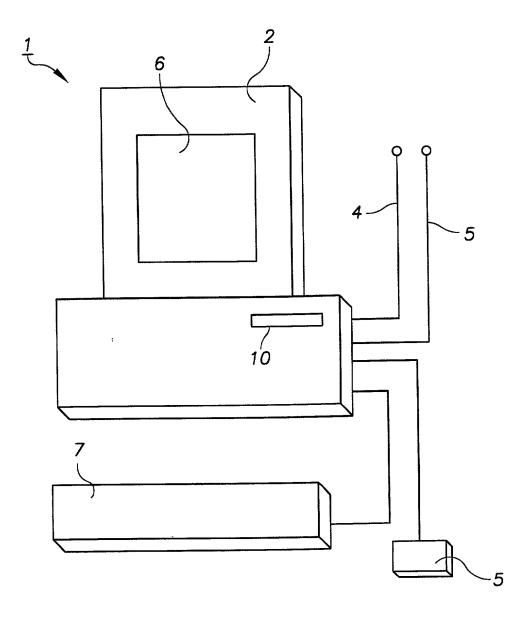
FIG. 1



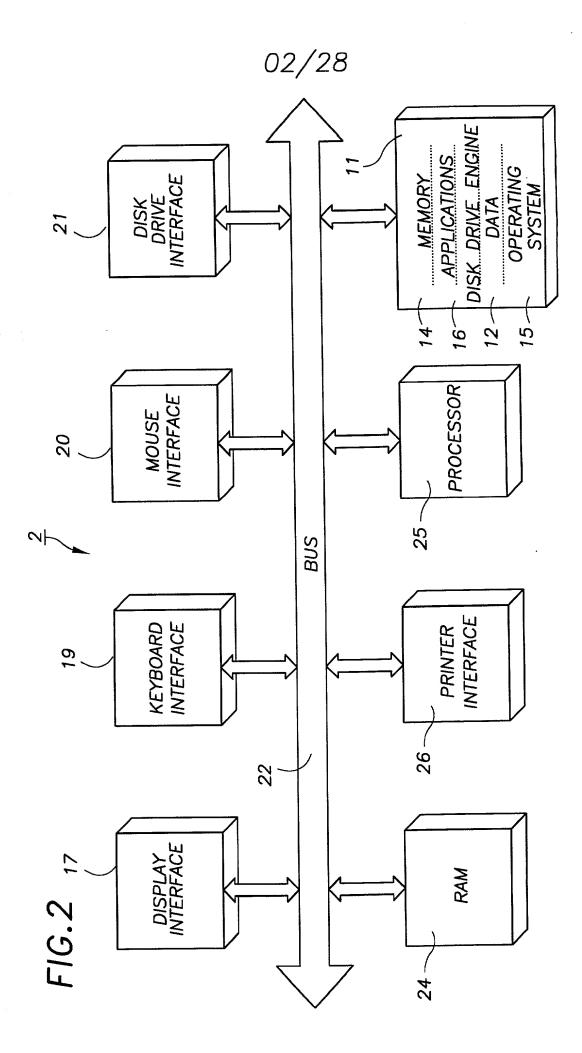
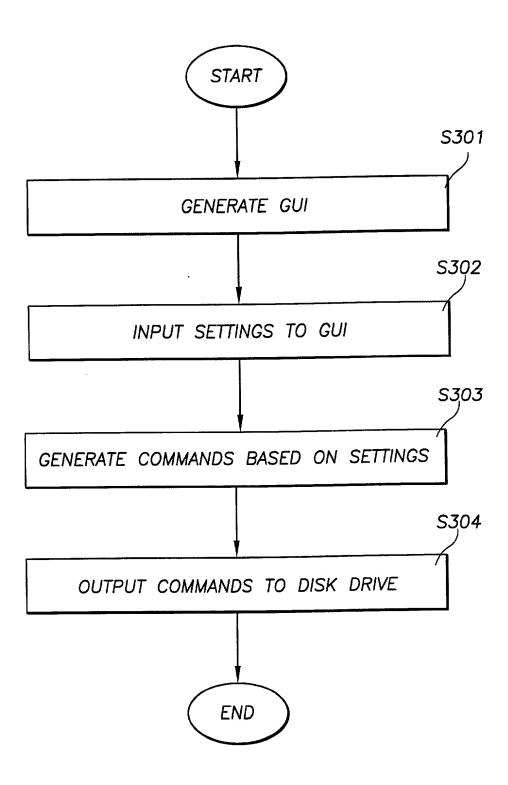
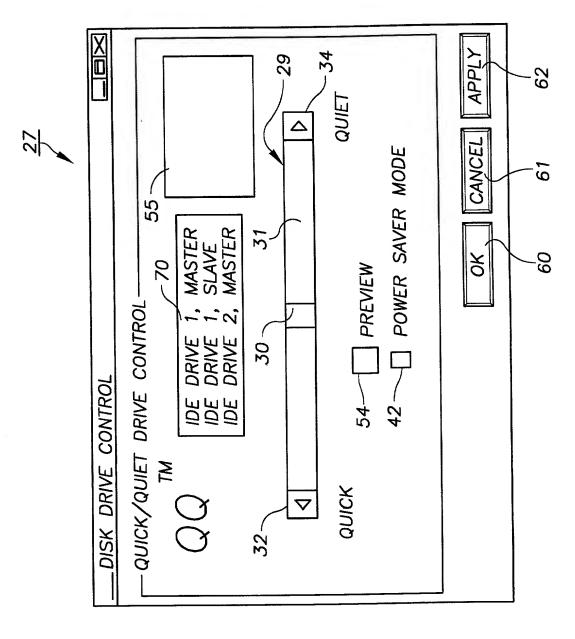


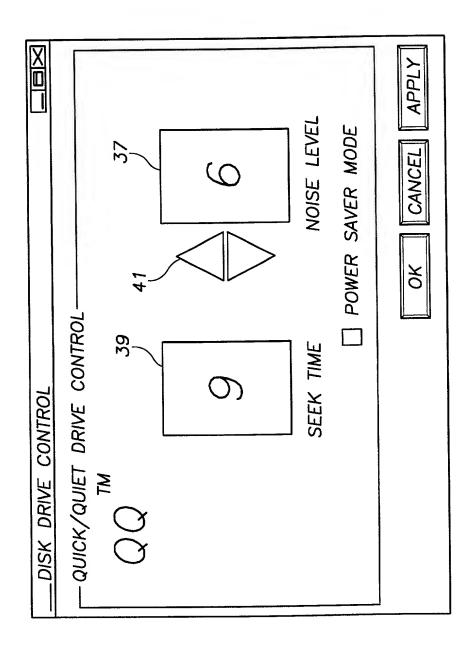
FIG.3



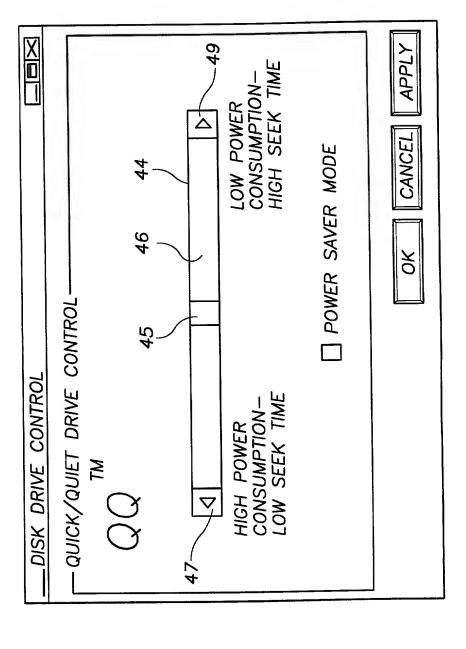


F1G.4

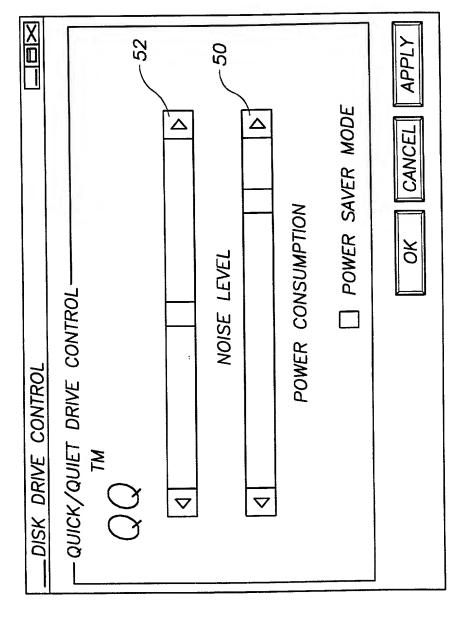
W. Charles



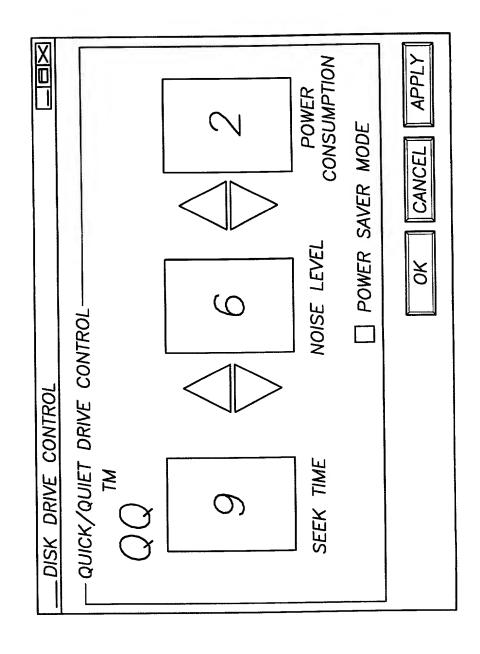
F1G.5



F1G.6



F1G.7



F1G.8

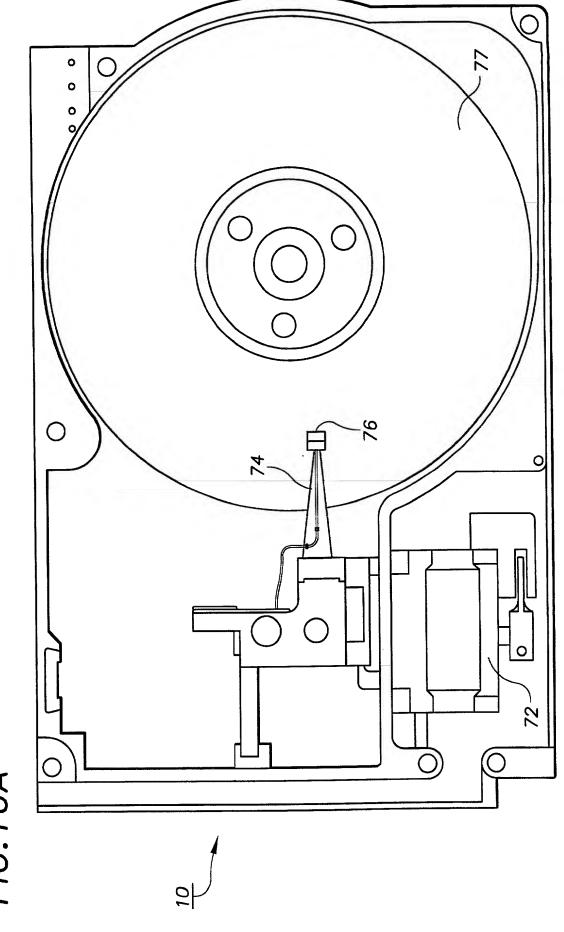
Commence of the Control of the Contr

F1G.9

IDE DRIVE 1, MASTER

IDE DRIVE 1, SLAVE

IDE DRIVE 2, MASTER



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FIG. 10A

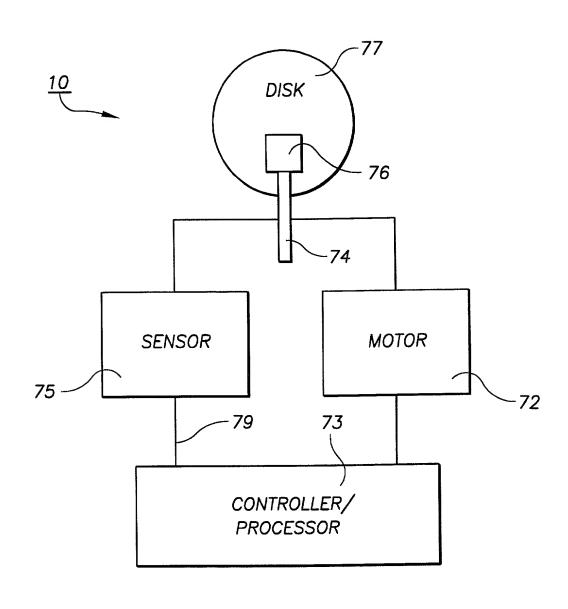
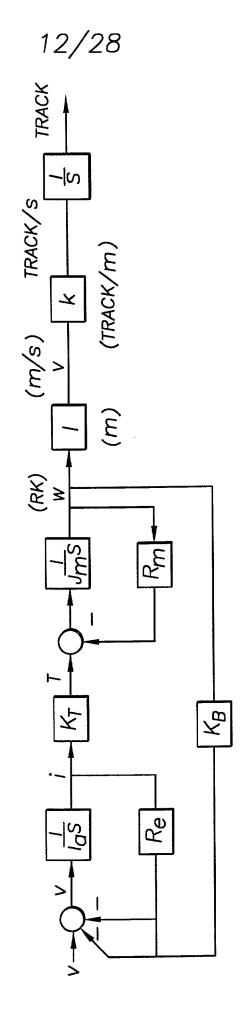
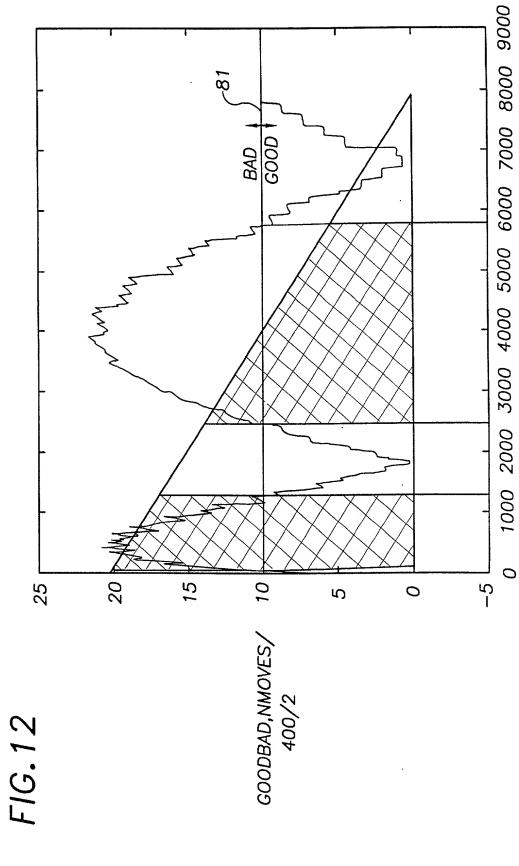


FIG. 11





MOVE DISTANCE (TRACKS)

FIG. 13 PRIOR ART

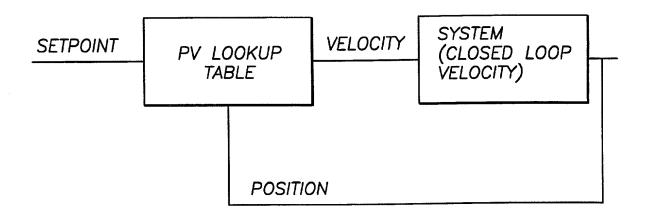


FIG. 14

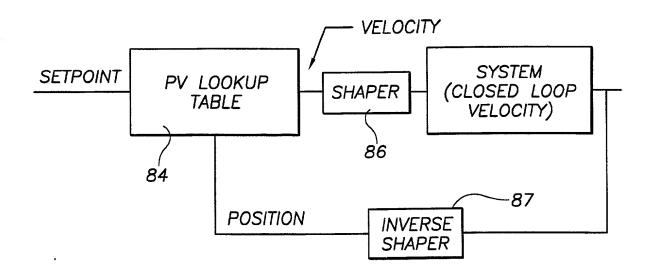


FIG. 15

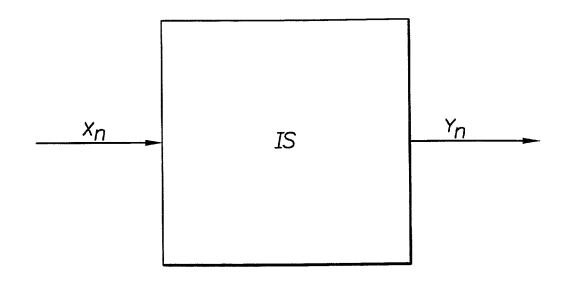


FIG. 16

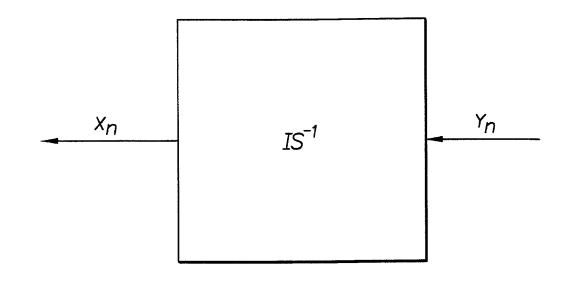


FIG. 17

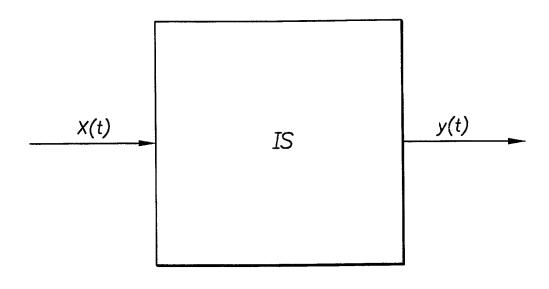
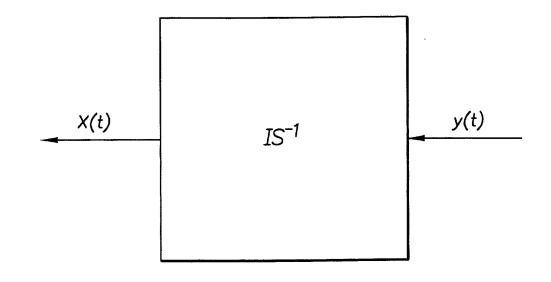


FIG18



The first start start start start start in the start s

FIG. 19

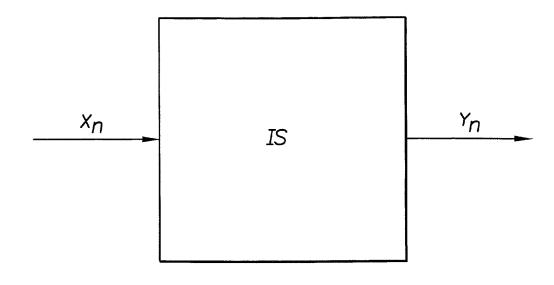
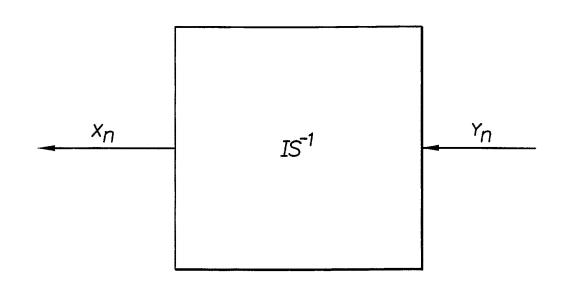
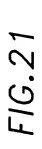
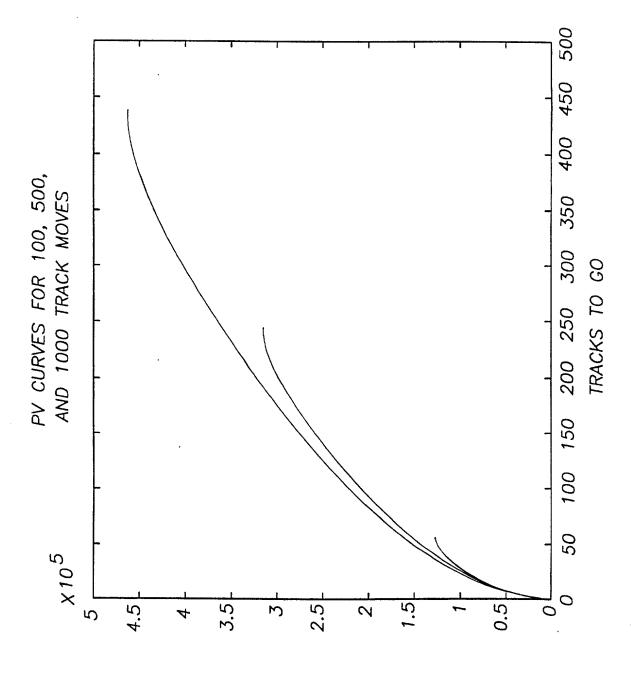


FIG20

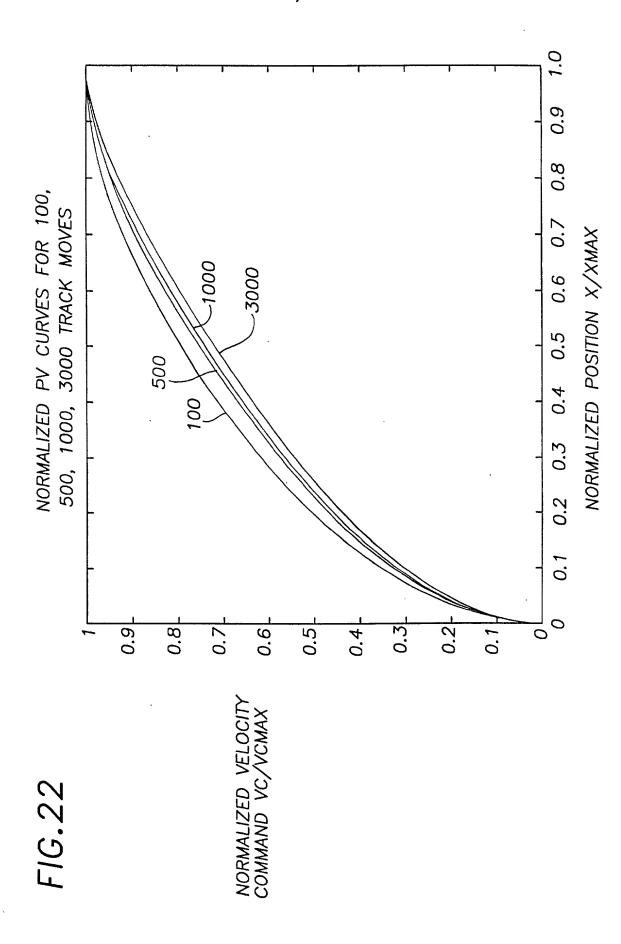




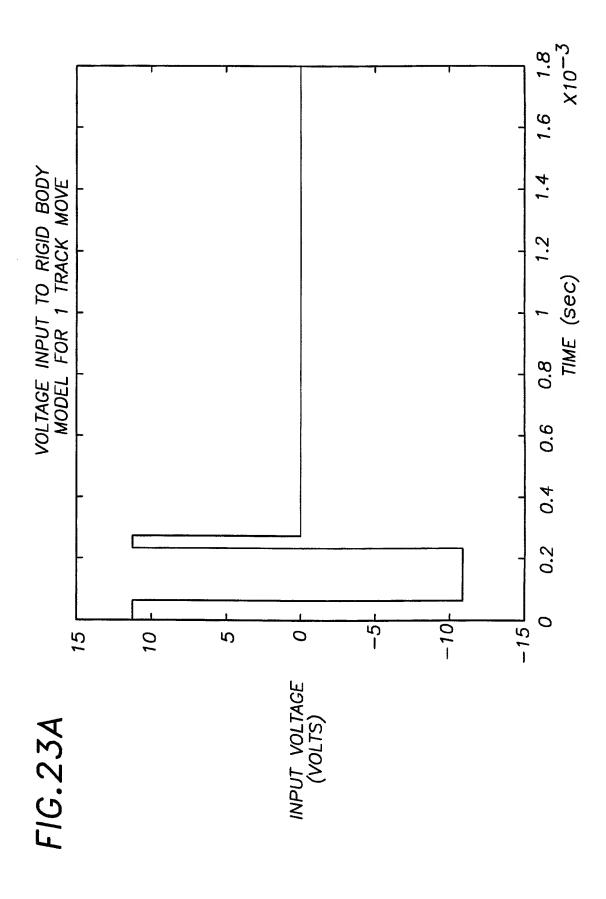


VELOCITY COMMAND (TRACKS/SEC)











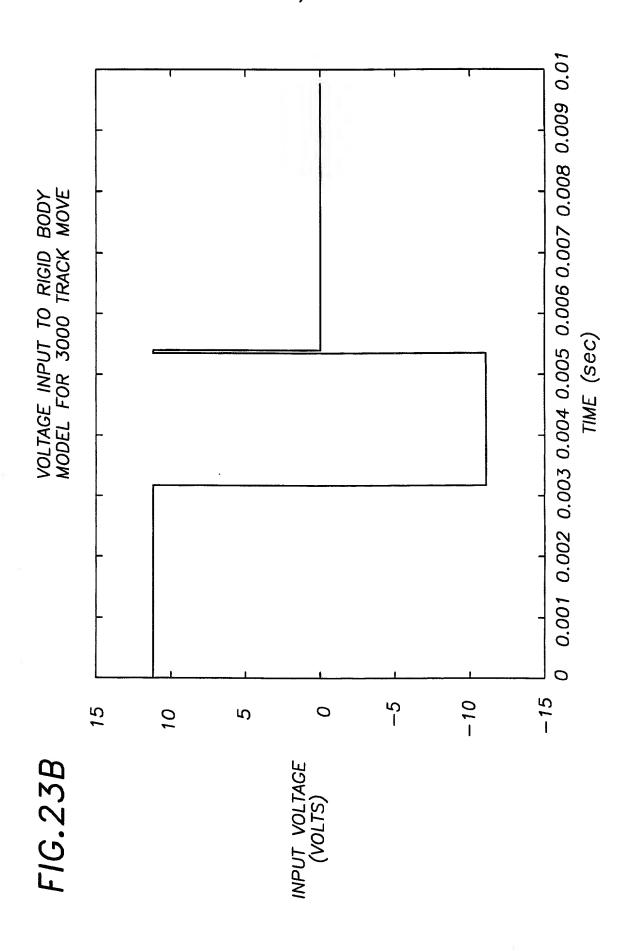


FIG.24

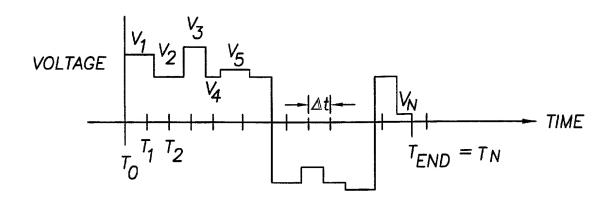


FIG.25

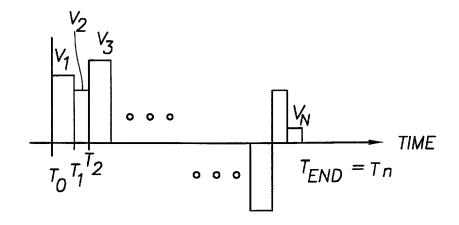


FIG.26

$$\begin{array}{c|c} V_1 & V_2 & V_N \\ \hline \hline T_1 & T_2 & + & \hline T_2 & + & \circ & \circ & + & \hline T_{END} \\ \hline T_0 & -V_1 & -V_2 & -V_N & \hline \end{array}$$

FIG.27

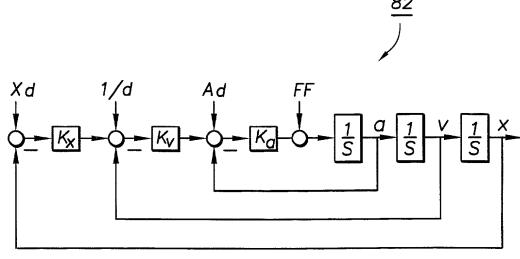
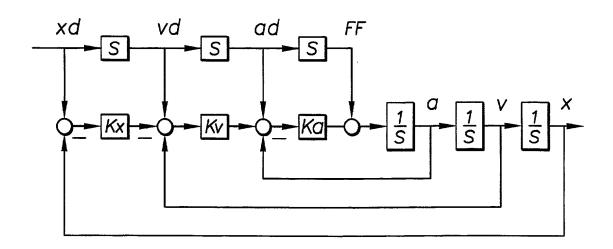
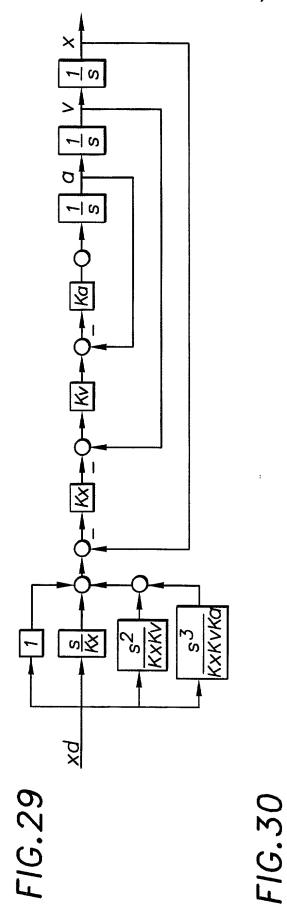


FIG.28





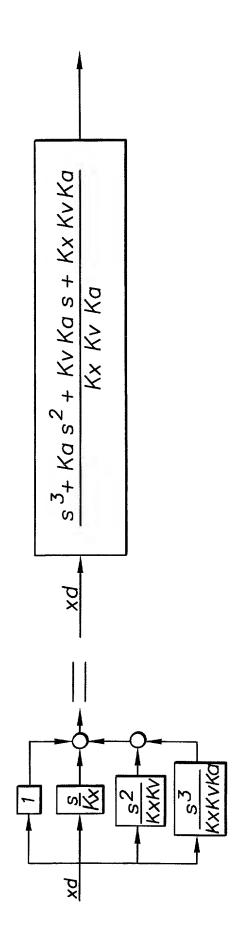


FIG.31

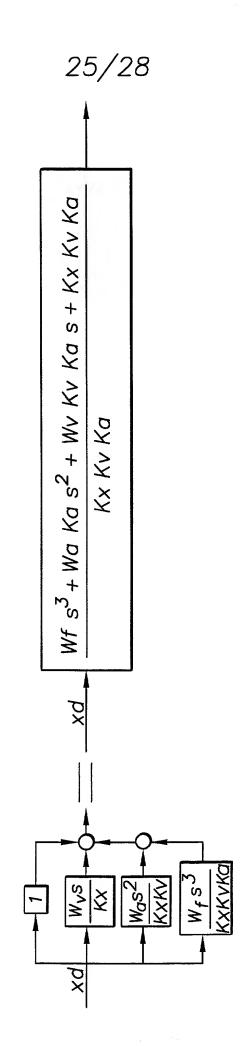
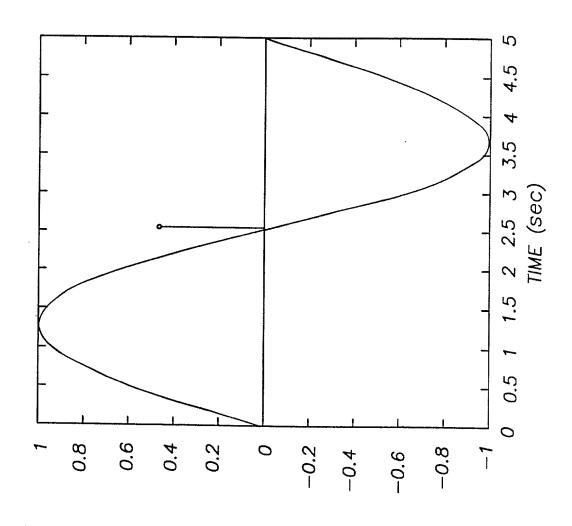


FIG.32



AMPLITUDE

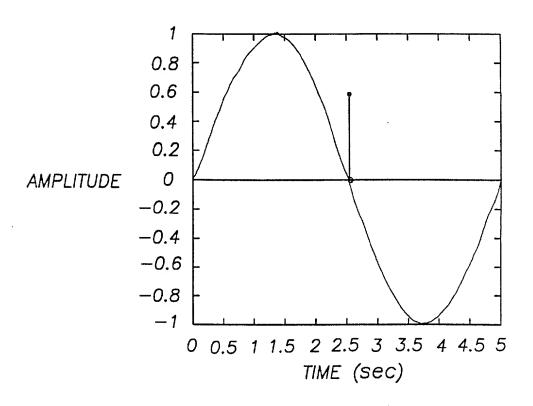


FIG.34

